PSI TCR-200/400 Series **Electric Actuator**

- O Ultra-small size, delicate appearance
- ◎ Rated torque: 200/400Nm
- Enclosure level: IP67
- ◎ Mechanical port: ISO5211 (F05/F07)
- Output shaft:
- $\ensuremath{\bigcirc}$ Adopt high performance brushless motor, overall actuator could be used 20,000 times *1
- % TCR series means whole plastic casing:PC+PET



	Product Model	Rated Voltage	Time	Additional Function	Remarks
	TCR-20/40N Normal on/off model	AC/DC24V AC95-265V	258	HTR(anti-condensation heater)	Dry contactor feedback Feedback signal is asynchronous with actual arrival
Contraction of the second	TCR-20/40C Intelligent on/off model	AC/DC24V AC95-265V	258	A(alarm signal output) HTR(anti-condensation heater)	Feedback signal is synchronous with actual arrival ¹² PUL speed adjustment PWM speed adjustment Double 096" OLED screen Perform 2-way/3-way/4-way mode
A CONTRACTOR	TCR-20/40T Intelligent modulating model	AC/DC24V AC95-265V	258	A(alarm signal output) HTR(anti-condensation heater)	Double 0.96° OLED screen Control feedback mode : 4-20mA/0-20mA/0-10mA 0-5V/1-5V/0-10V/2-10V '3
B ee	TCR-20/40B Intelligent bus model	AC/DC24V AC95-265V	258	A(alarm signal output) HTR(anti-condensation heater)	RS485, CANBus2.0 Double 0.96" OLED screen On/Off model has PUL Bus on/off model(ON/OFF/B33) Bus modulating model, modulate precision is 1%
	TCR-20/40R Intelligent wireless model	AC/DC24V AC95-265V	25S	A(alarm signal output) HTR(anti-condensation heater)	Wireless ON/OFF model(ON/OFF) Double 0.96" OLED screen Wireless modulating model, modulate precision is 1% Communication frequency: 433/868/915MHZ LORA: The max is 2.5km (cleared area) ENOCEAN:20-100m ⁴

- Test condition: Rated load, test at factory environment of 25°C temperature and 50% humidity, lead the result from 2 times switching cycle, which will be influenced by different toad and working environment.
 The relay feedback is dry feedback signal, which will be disappeared when power-cut, and then will be recovery when power-on.
 The control terminal adopts two ways independence input: One way is 0–10V,2–10V,0–5V,1–5V. The other is 0–20mA,0–10mA,Both could be selected by menu. The feedback terminal also adopts two ways independence output: One way is 4–20mA, the default is output. The other is 2–10V, the default is output .
 Both of them could be changed to 0–20mA of 0–10V output.
 The Could be changed to 0–20mA of 0–10V output.
 The Other is 2–10V, the default is output .
 The vertex of 0–10V output.
 The Other is 2–10V is 2–10V, the default is output .



The influence of speed adjustment to torque, the lower speed ,the smaller torque ,the max will be reduce more than 35%. Speed adjustment has little influence to torque, the torque would be reduce about 15% Anti-condensation heater, built-in module, when the internal temperature is below 25%, the actuator will turn on heating function, which power is 2W. Means fault feedback signal, which is relay dry feedback signal.



Lora Controller

Ocean Controller



PWM: PUL: HTR:

